

VON DER KARTE ZUM AUTONOMEN FAHREN



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SiteOwner TomTom Berlin

2. Forum "Neue Mobilitätsformen"

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TOMTOM 



a **TOMTOM** company



Autonomos History Overview



2007
DARPA Grand Challenge
FU Berlin



2010
Autonomos Labs
FU Berlin



2012
Smart Safety Systems
Autonomos GmbH



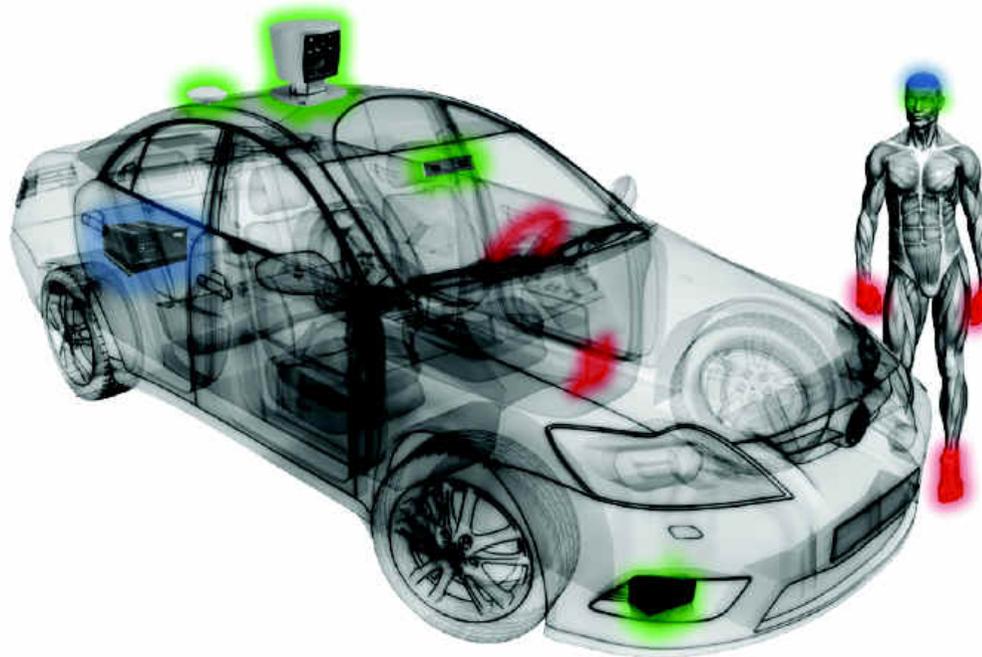
2015
Maps for AD



2017
Part of the
TomTom Family

Grundprinzip der Robotik

Sense – Plan – Act



Wahrnehmen

Augen
Sensoren

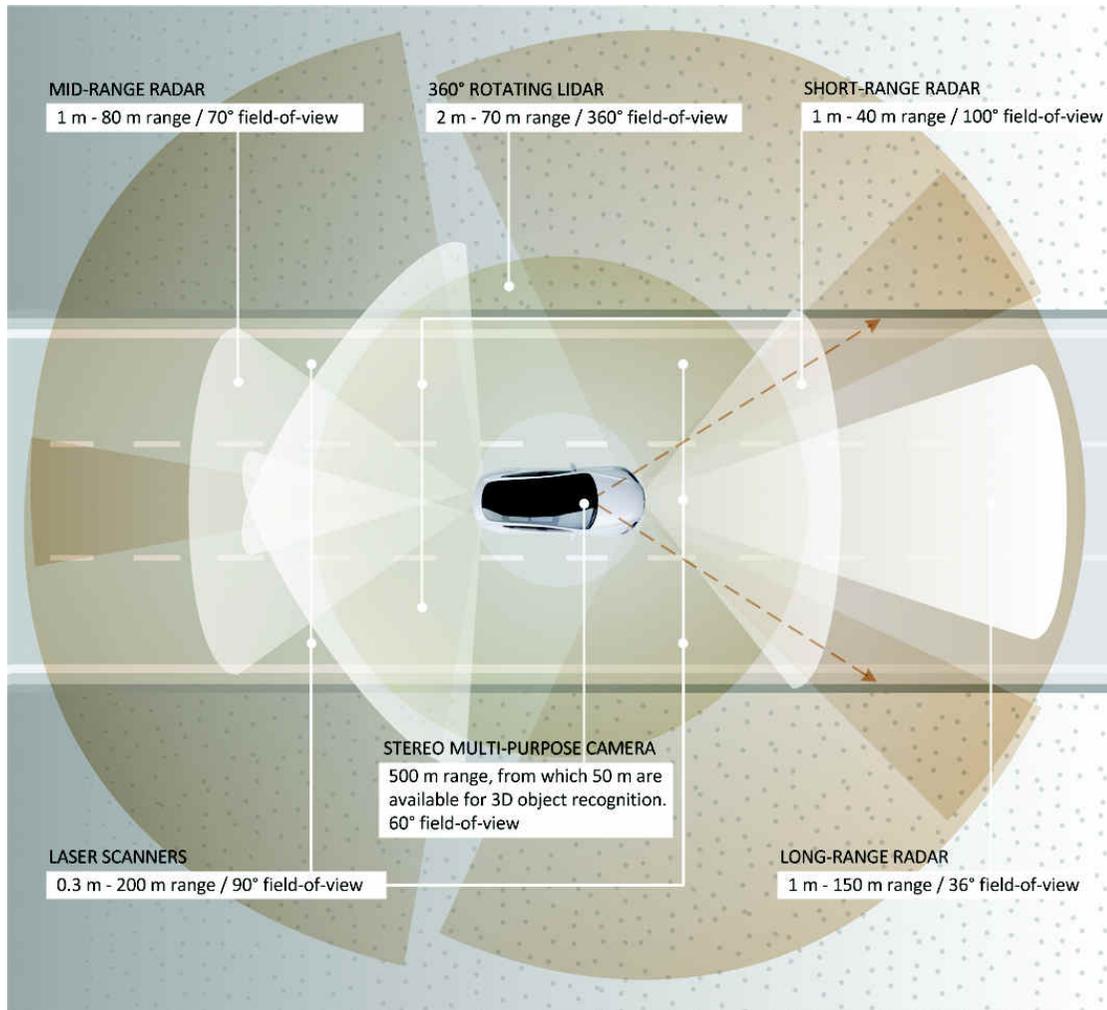
Planen

Gehirn
Computer

Ausführen

Muskeln
Aktorik (Lenken, Gas, Bremse)

Was ist hinter dem eigenen Horizont?



HD Maps
& C2X

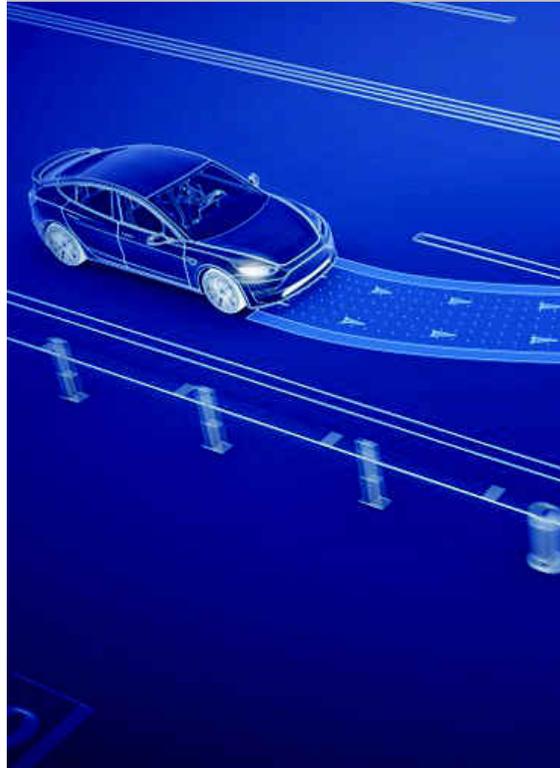
Die Säulen des automatisierten Fahrens

Sensing



Tom

Driving policy

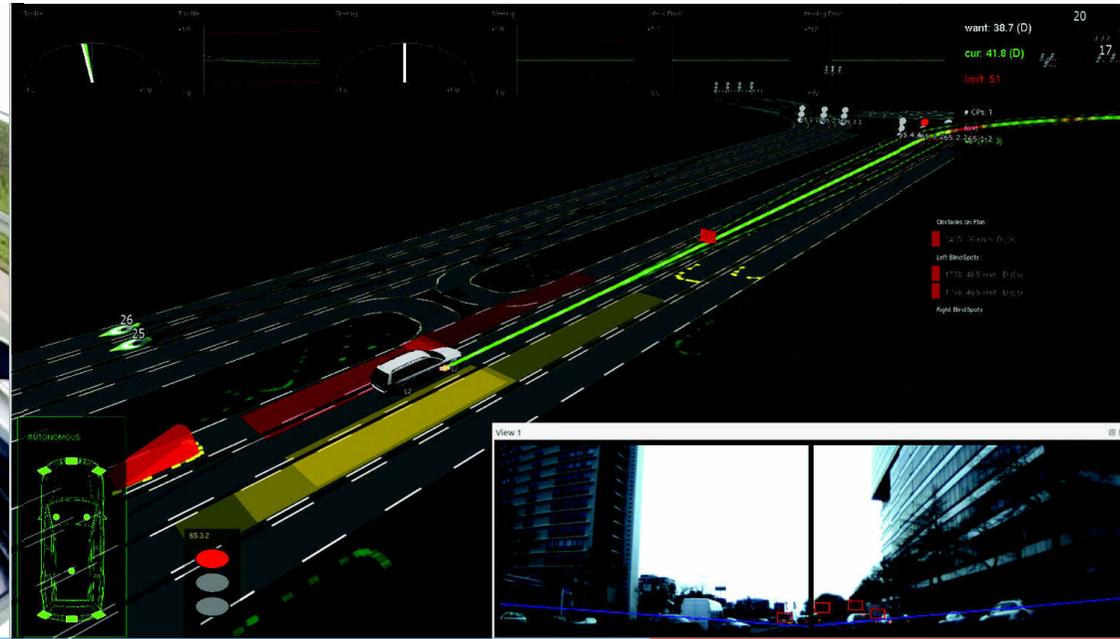


Actuators



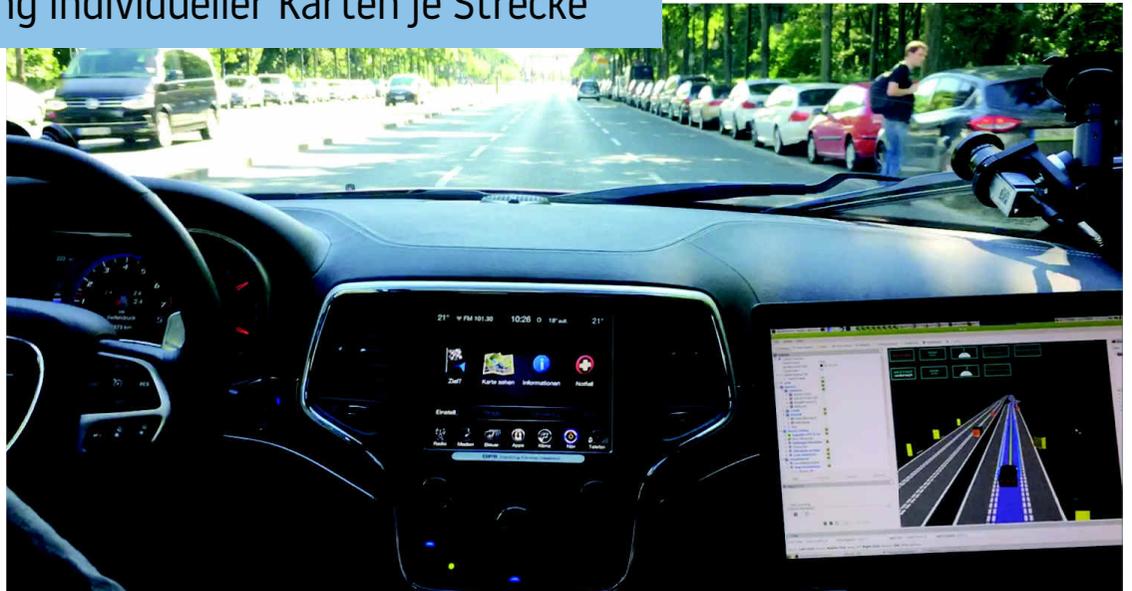
Erprobungen auf geschlossenem Areal – Verhalten des Fahrzeugs optimieren





Straßentests in Berlin – Vorbereitung individueller Karten je Strecke

AUTOMATISIERTES FAHREN IST NUN REALITÄT



Ausnahmegenehmigungen für Straßentests

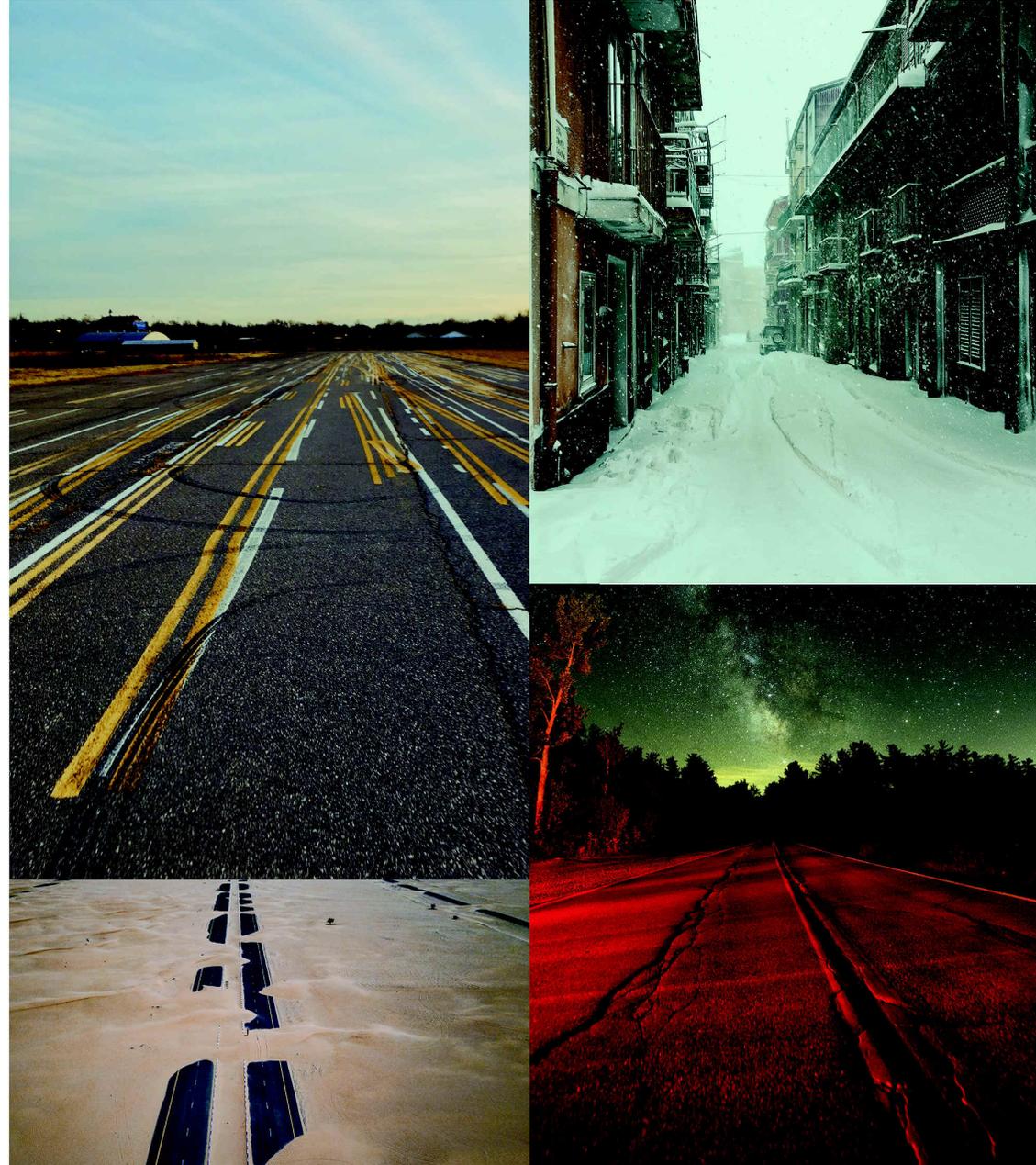


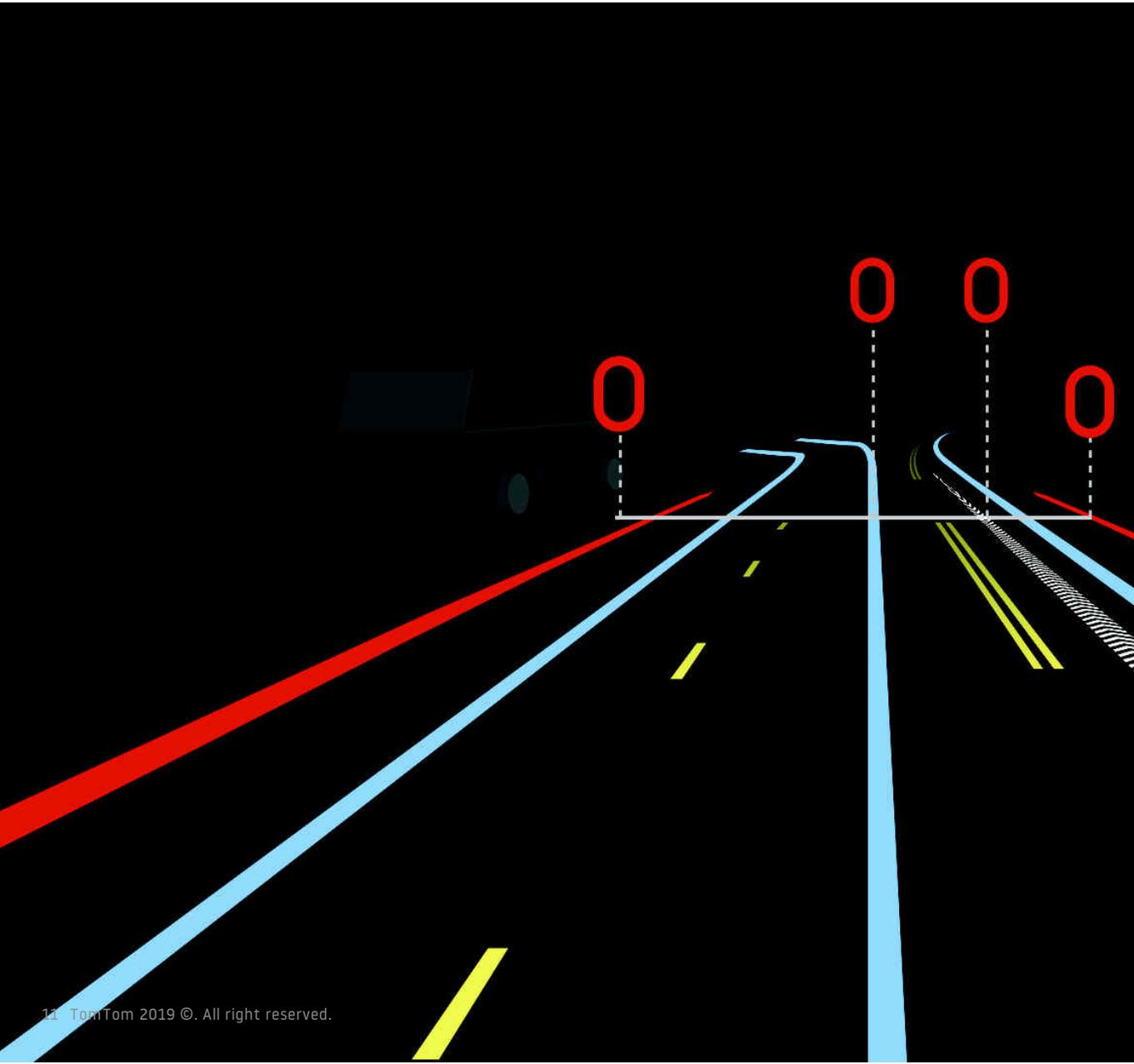
Straßentests Mexiko City 2012
Andere Länder andere Sitten



Maps complement sensors to ensure high reliability

Maps are not affected by adverse weather conditions, working even when sensors can't function properly, for greater safety



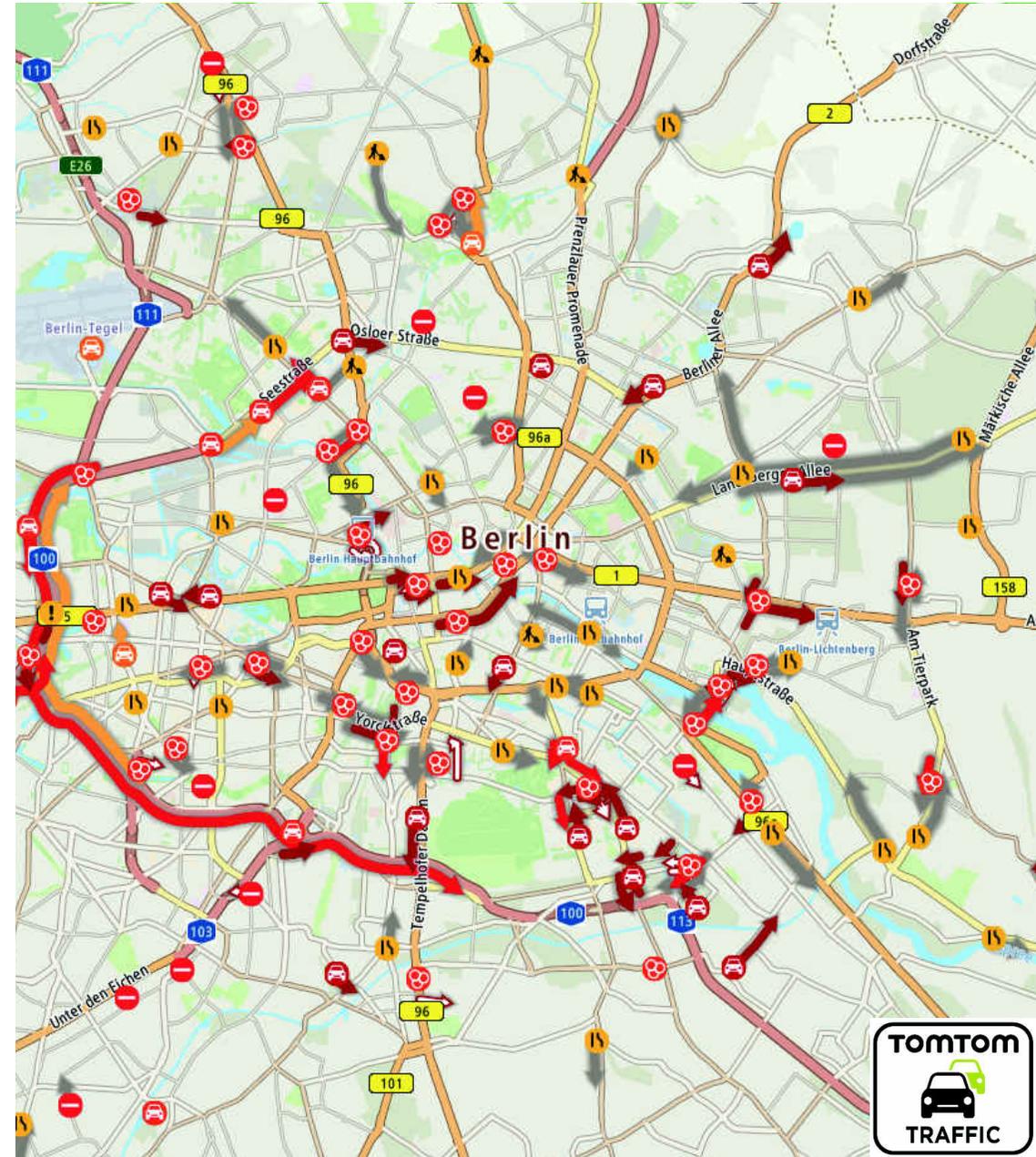


Maps help automated vehicles understand the environment

Maps help automated vehicles see well beyond the range of the sensors, and help the vehicle *understand* what the sensors see.

Maps form the basis for sensor data aggregation

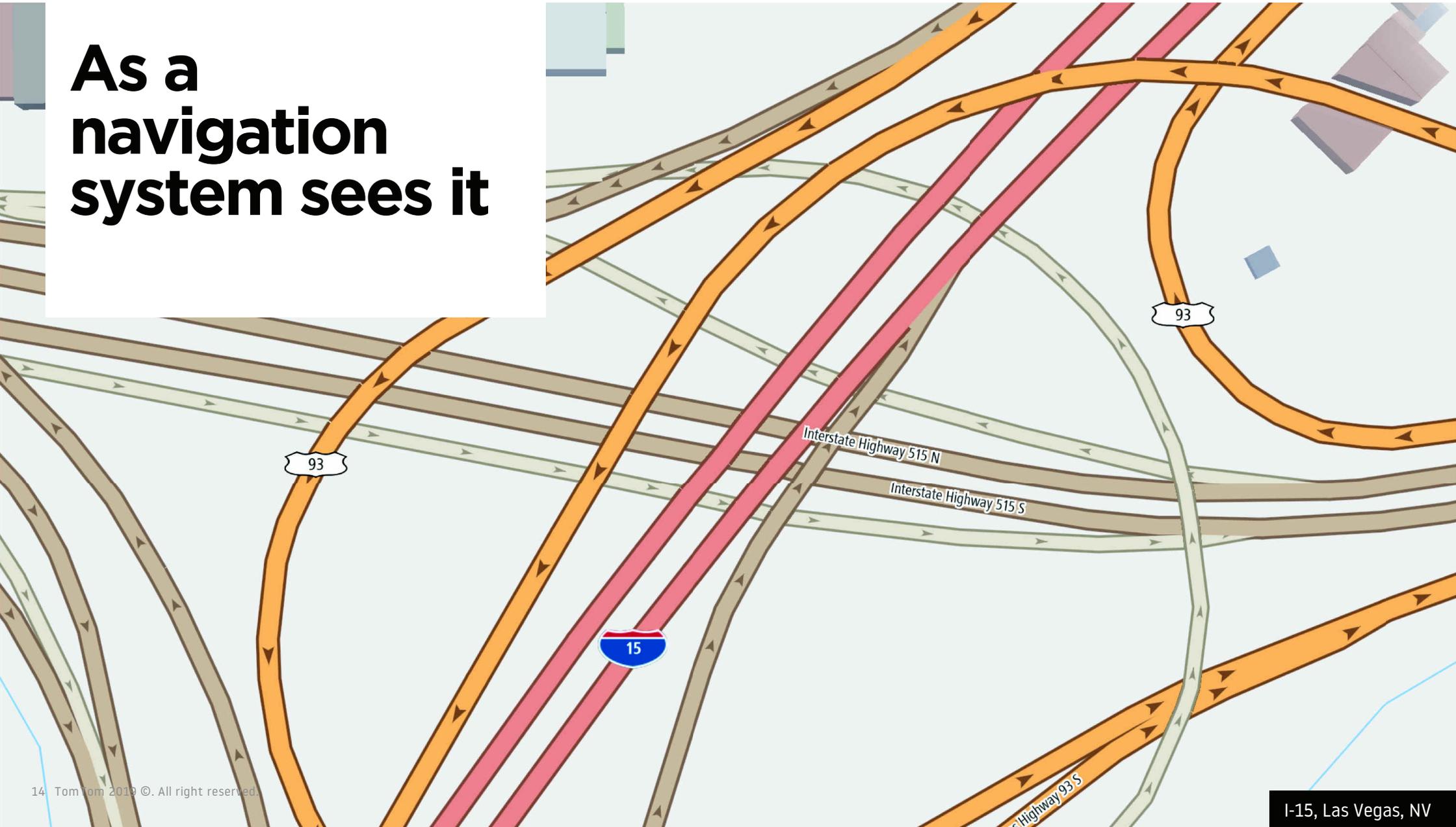
Maps act as the foundation to aggregate and derive value from sensor data crowdsourced from vehicles



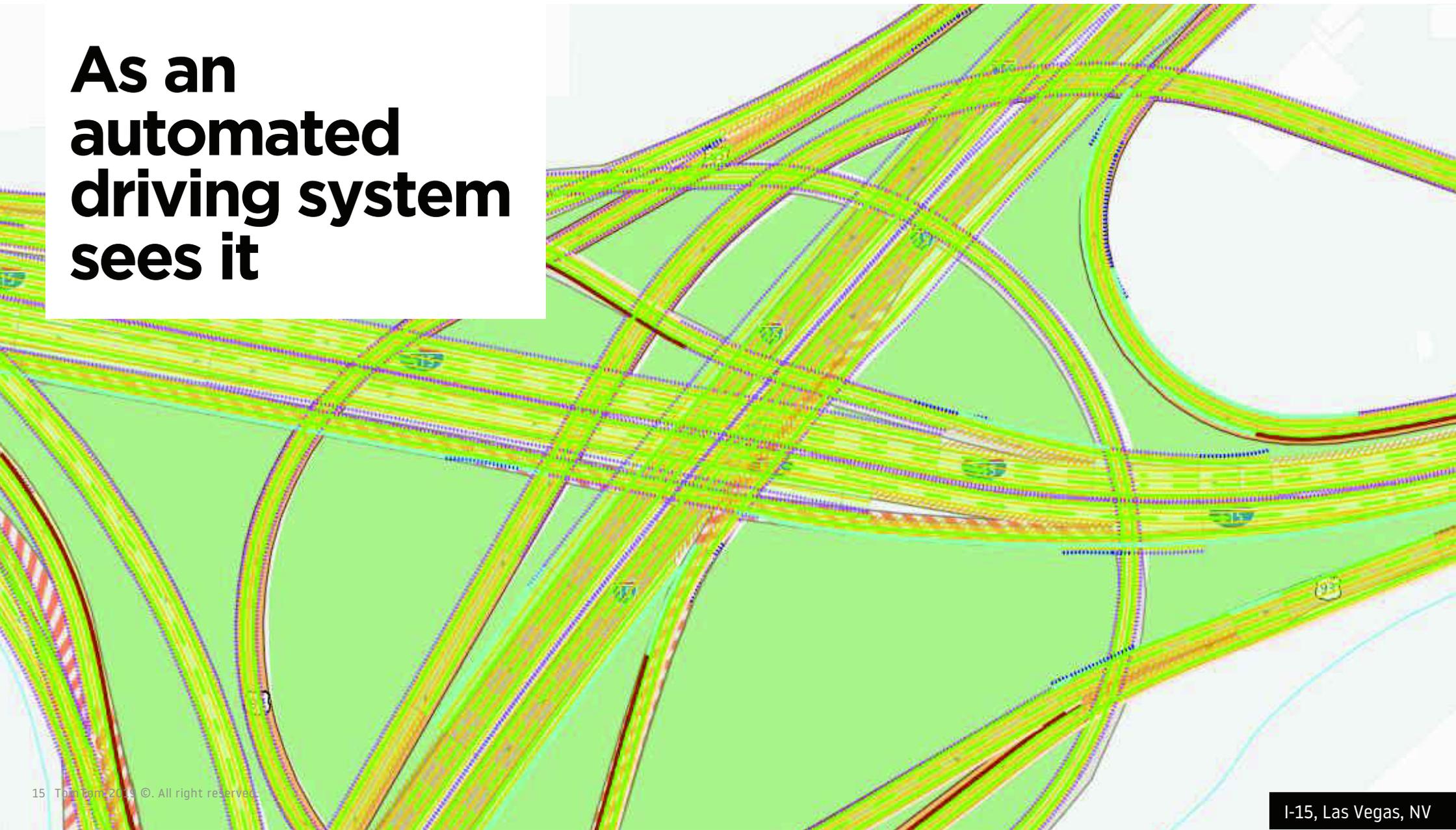
The road as we see it



**As a
navigation
system sees it**



**As an
automated
driving system
sees it**



TomTom focuses on mapping for autonomous driving

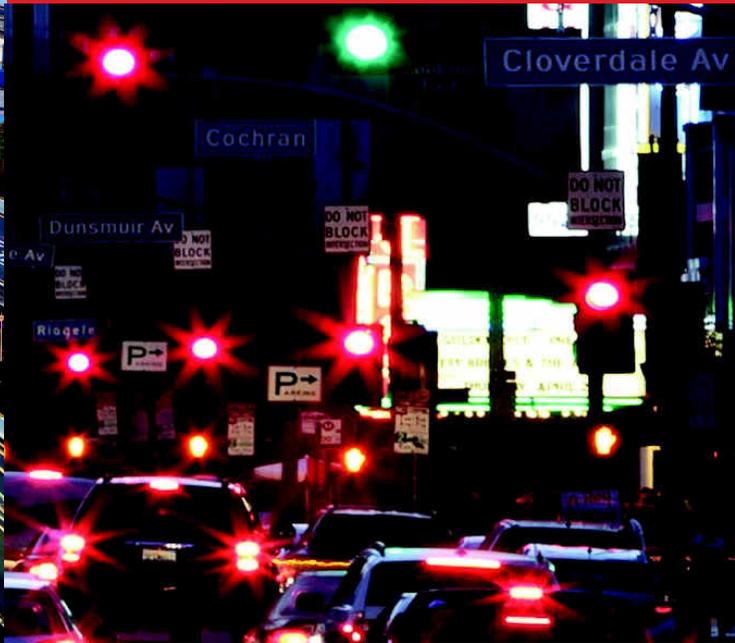


The role of HD Maps in automated driving

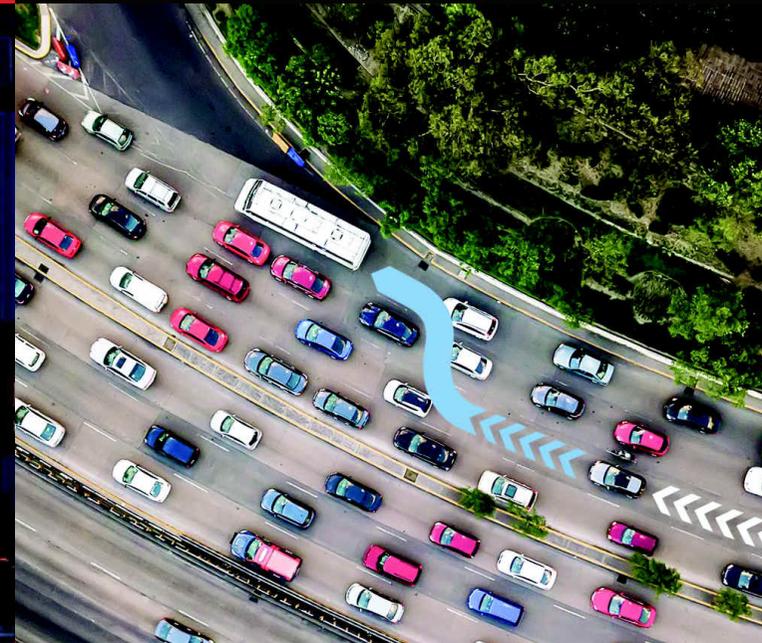
Localization



Perception

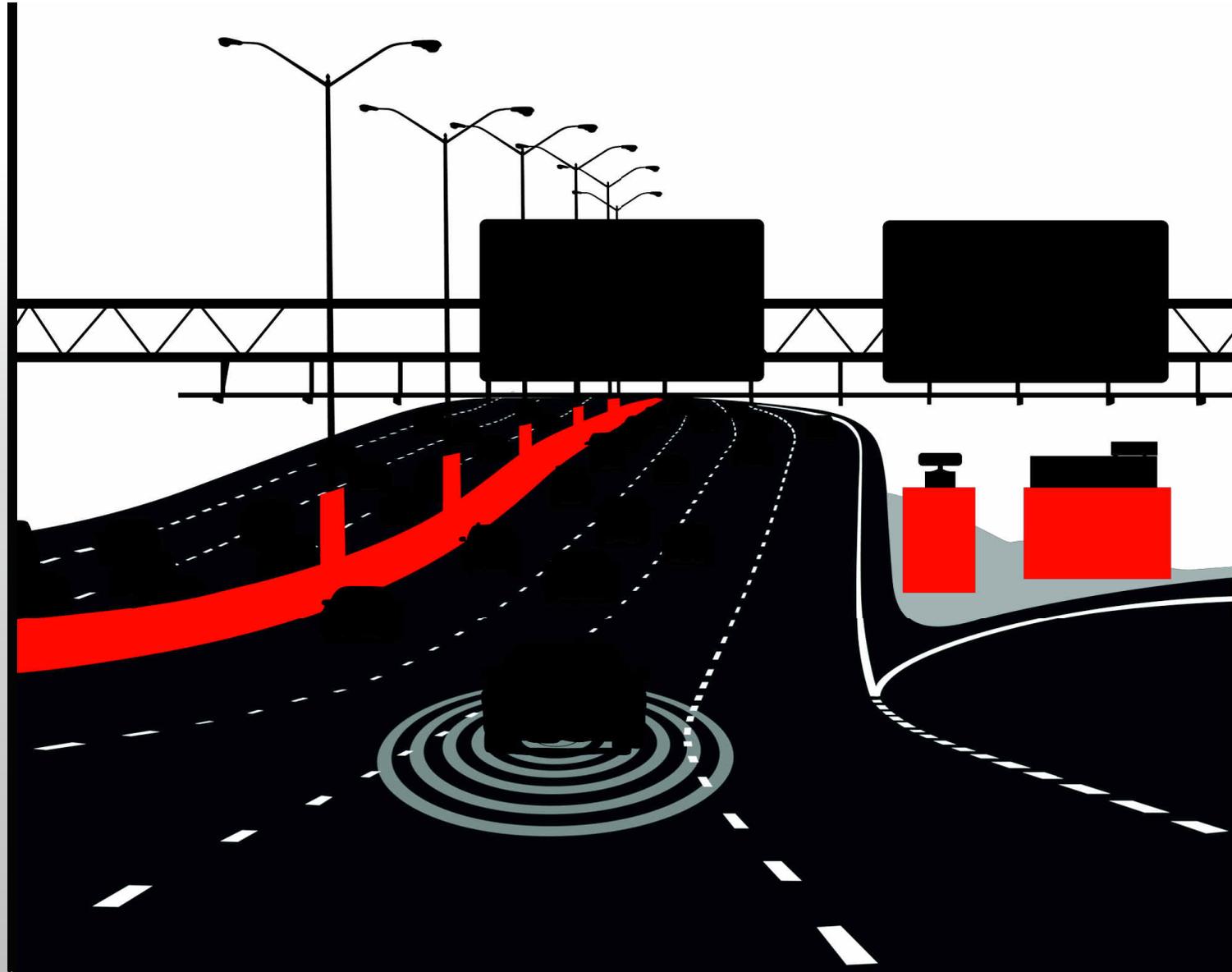


Path planning



RoadDNA Suite

Powers sensor-agnostic localization



Mobile mapping

VELODYNE LIDAR COLLECTS
700,000 DATA POINTS
PER SECOND DELIVERING AN ACCURACY TO
WITHIN 2 CM



2 SICK LIDARS
SUPPLEMENT VELODYNE
ENSURING COMPLETE
**CAPTURING OF
ROAD SURFACE
& FURNITURE**



INTERNAL COMPUTER
PROCESSES
1 TERABYTE
OF DATA DAILY



THE LADYBUG 5 COLLECTS
**3.8 BILLION
PIXELS PER KM**
THAT ARE USED TO VALIDATE
REAL-WORLD CHANGES



THE COMBINATION OF
2 DGPS ANTENNAS,
INERTIAL SENSORS AND
THE ODOMETER ENSURE
**HIGHLY
ACCURATE
POSITIONING**

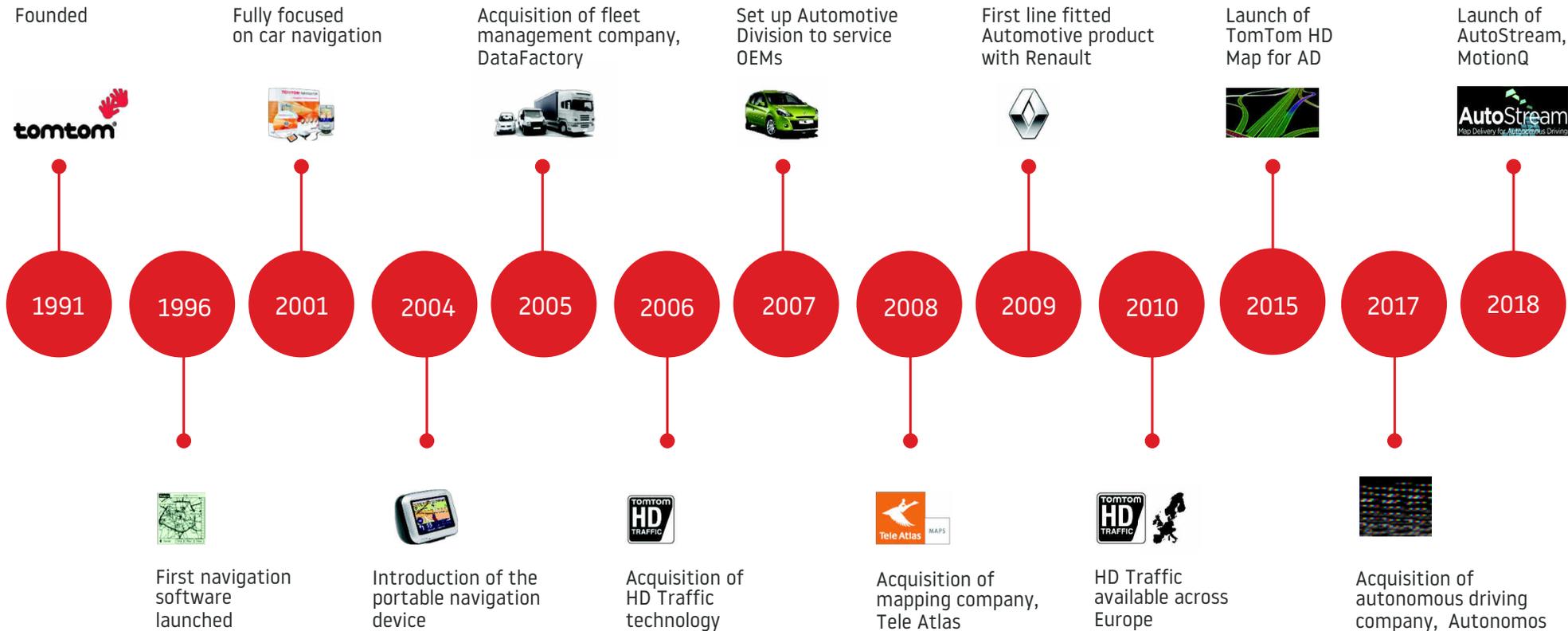
3+
MILLION KM
DRIVEN BY MOBILE
MAPPING VEHICLES
EACH YEAR

The future of driving, now.

automotive.tomtom.com



Our 27-year focus on navigation technologies



Our vision

**is to build the most advanced map-as-a-service
to help make autonomous driving a reality**

THE LOCATION TECHNOLOGY SPECIALIST.



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SHAPING MOBILITY
AND AN AUTONOMOUS FUTURE
WITH NAVIGATION SOFTWARE,
REAL-TIME MAPS AND SERVICES